Introductory Tutorial to *Mathematica* 8

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This introductory tutorial to *Mathematica* 8 is designed as interactive course material and should ideally be worked through together with students at PCs. Each student should progress sequentially through all Input/Output. Duration: approx. 90min.

Getting Started with Mathematica

Mathematica Basics

Some Basic Remarks

Mathematica allows analytical, numerical and grafical calculations. *Mathematica* offers a relatively simple and instructional logical syntax. Most of the known functions do have a syntactically similar correspondent in *Mathematica*. The argument of a function always is to set inside square brackets (e.g. Sin[x]). If you operate on some mathematical expression, also the operation is executed onto brackets and the arguments are separated by commas (e.g. Integrate[f[x],x]).

Data types

The standard data type, the Notebook (.nb) provides an interactive interface in which calculations are possible. Under *File -> Save As* there are some further data formats to which the notebooks can be exported (.tex, .html, .txt, .pdf). Also single expressions can be copied as IAT_EX code and be pasted into a .tex-file. Notebooks can be opened by *Mathematica* (interactive) or the *MathReader* (read only) respectively the *Wolfram CDF Player* which is available as free internet browser plugin. The forward- and backward-compatibility is given partially, which means that notebooks created in *Mathematica* 7 will usually run in *Mathematica* 8, the opposite direction will rather cause problems.

Wolfram|Alpha

Wolfram|Alpha is a net-based "frontend" for *Mathematica* usage with a huge database of knowledge. Describing as "scientific Google" does not really cover its whole power. Either you access it via the website www.wolframalpha.com or there is even an integration to *Mathematica*. Beginning an Input with the "=" sign is interpreted as Wolfram|Alpha query. E.g: "= cosmological redshift z=3"

Assuming reusinit-wavelengti	h formula Use cosmological redshift instea	ıd
Calculate emitted wavelengt	h -	
observed wavelength: 575	onm 🗧	
Assuming observed waveleng	th and emitted wavelength and emitted frequency instead	
Also include: dark energy den	isity, matter density and radiation density	
	ble parameter	
nput information		
nput information:		
nput information: redshift-wavelength f	ormula	
	ormula 3	
redshift-wavelength f	3	
redshift-wavelength for redshift	3	
redshift-wavelength for redshift observed wavelength	3	More
redshift-wavelength for redshift	3	More
redshift-wavelength for redshift observed wavelength	3 575 nm (nanometers) 143.8 nm (nanometers)	More
redshift-wavelength for redshift observed wavelength	3 575 nm (nanometers)	More

Т Т 4	$c - \lambda_e$
λ_e	emitted wavelength
z	redshift
λ_o	observed wavelength

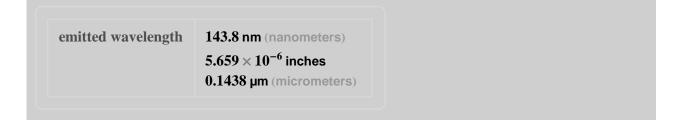
Cosmological results:

8

More

11.5 billion years					
2.19 billion years					
21.1 billion ly (light years)					
6480 Mpc (megaparsecs)					
2×10^{23} km (kilometers)					
$1.24 imes 10^{23}$ miles					
0.453					
0.25 × current value					
matter dominated, post-recombinatio					
10.9 K (kelvins)					
bda-CDM model; current universe age: 13.7					

Big Bang	5 billion years	10 billion years	present
first galaxies form		Earth forms	



Input/Output I

The input of commands in *Mathematica* is done via the Enter key (not Return), which is either located at the numeric keypad or it can be typed in as Shift + Return. Each Output and Input is numbered by *Mathematica*.



In this way one can refer to previous In- and Output

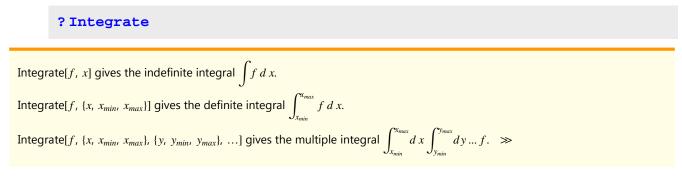
```
In[2] + Out[2]
6
```

respectively one can refer to the last output via %.



Help / Documentation Center

Mathematica provides a compresensive help and documentation center which gets completed by the online-documentation. By entering the F1 key, the documentation center is opened; one can even mark an expression in the notebook and will get to the help entry for this term via F1. For a brief summary of syntax usage and functionality of a function, one can also just enter question mark + function to get an overwiev.



With ?xyz* one gets a list of functions starting with xyz.

? Integ	*				
▼ System`					
Integer	IntegerExpon- ent	IntegerPart	IntegerQ	IntegerString	Integrate
IntegerDigits	IntegerLength	IntegerPartiti- ons	Integers	Integral	

The Kernel

Mathematica "remembers" all definitions, In- and Outputs inside a Notebook. As described some lines before, one can refer to previous terms easily. As long as the Kernel is running, all these definitions are available.

? Random

Random[] gives a uniformly distributed pseudorandom Real in the range 0 to 1.

Random[type, range] gives a pseudorandom number of the specified type, lying in the

specified range. Possible types are: Integer, Real and Complex. The default range is 0 to 1. You

can give the range {min, max} explicitly; a range specification of max is equivalent to {0, max}. \gg

```
a = Random[Integer, 100]
b = Random[Integer, 100]
c = Random[Integer, 100]
22
53
3
a + b + c
78
```

If you want to delete entires in this memory of definitions, the Clear[Arguments] command can be used. If you want to clear all kernel memory, i.e. kill and restart the kernel, then go to *Evaluation -> Quit Kernel -> Local*. This also terminates running calculations which comes in handy, when you realize that a calculation seems to have got stuck and you don't want to wait any longer.

?Clear

 $Clear[symbol_1, symbol_2, ...]$ clears values and definitions for the $symbol_i$.

 $\mbox{Clear}["{\it form}_1", "{\it form}_2", \, \ldots]$ clears values and

definitions for all symbols whose names match any of the string patterns $form_i$. \gg

```
Clear[a, b, c]
a+b+c
a+b+c
```

If one wishes not to quit ther kernel but delete all previous definitions, (of all currently opened *Mathematica*-Notebooks) the syntax is as follows.

```
Clear["Global`*"]
```

Comments

Comments (i.e. non to be executed, read-only text parts) inside Input-lines can by typed inside round brackets and stars.

```
Sqrt[2] ==
(* Square root of 2 can also be typed via "Ctrl + 2": *) \sqrt{2}
True
```

Shortcuts

There is a number of shortcuts and hotkeys in order to simplify typing formulas to the notebook. Some examples:

```
a_{i} (* \text{ Subscript via "Ctrl + -" *});
\frac{1}{2} (* \text{ Fraction lines via "Ctrl + /" *});
\int (* \text{"Esc + int + Esc" *})f[x] dx (* \text{"Esc + dd + Esc" *});
\infty (* \text{"Esc + inf + Esc" *});
\alpha (* \text{ Also greek letters via "Esc + Letter + Esc" *});
```

+

Syntax Highlighting

When typing formulae in a *Mathematica* notebook, syntax highlighting is very convenient. Known Functions, trailing brackets, arguments etc. are recognoized and highlighted; either as positive feedback that everything is alright or - usually even more helpful - as negative feedback that there is some syntactic problem. In case the syntax is faulty, klick on the plus-sign on the right hand side of the input line to get more information about what might be wrong.

```
Solve \left[ Sin \left[ x_{+} + 3 + Cos \left[ x_{-} \right] = 1, y \right] \right]
```

Symbolic Calculus in Mathematica - Basics

Input/Output II

The decimal separator is the dot (.) verwendet, not the comma. A space character is interpreted as scalar multiplicator ("times") and replaced by a cross.

3.14 × 3.14 9.8596

Definitions and Assignments

The simplest form of assigning a right hand side to a left hand side was already presented, namely the equal sign.

? =

lhs = *rhs* evaluates *rhs* and assigns the result

to be the value of *lhs*. From then on, *lhs* is replaced by *rhs* whenever it appears.

```
\{l_1, l_2, ...\} = \{r_1, r_2, ...\} evaluates the r_i, and assigns the results to be the values of the corresponding l_i. \gg
```



One can surpress the otput of an assignment by adding a colon. This assignment is evaluated not until the definition is being used somewhere later in the Notebook. This assignment is especially useful when the right hand side is somewhat elongate and evaluation costs computation time. ?:=

lhs := *rhs* assigns *rhs* to be the delayed value of *lhs*. *rhs* is maintained in

an unevaluated form. When *lhs* appears, it is replaced by *rhs*, evaluated afresh each time. \gg

f := 1

Functions + Pattern

One main powerfulness of CAS such as *Mathematica* is symbolic calculus, i.e. working with functions. There is one little syntax peculiarity of *Mathematica* concerning this topic. Objects with arguments in the form f[x] are static; if you want the argument to be variable, then definition of the function must add an underscore (see *Mathematica* documentation center under keyword Pattern) to each argument that should be a variable.

DONT :

DO:

h[x] := Sin[x]	
h[1]	
h[1]	
$g[x_] := Sin[x]$	
g[1]	
sin[1]	

As you can see, *Mathematica* does not necessarily output numerical values. In this case, the result is an irrational number and one needs to specify further if and what numerical outoput is wanted.

Input/Output III

In order to force numerical output, one needs to type N[Argument, Digits].

N[g[1], 100]

0.8414709848078965066525023216302989996225630607983710656727517099 919104043912396689486397435430526959

There is also the possibility to append functions and objetcs that operate on the whole expression by a double slash.

g[1] // N 0.841471

Basic Calculus (Scalars)

An addition of objetcs (scalars as well as vectors and matrices) is typed - as expected - via the plus (+) key, subtraction via minus (-). Scalar multiplication can be set via the star (*) or a blank character, division is typed viaone slash.

2 * 2		
4		
2 × 2		
4		
2 / 2		
1		

Nested expressions are typed as "with pen and paper" using round brackets.

(1 + (4 - 3) * 2) / (1 + 1) + 1

5 --2 Clear["Global`*"]
(* please enter this input to delete all previous definitions
which would partially conflict with the upcoming section *)

Basic Commands - I/O III

Until now we have seen *Mathematica* mainly as somewhat sophisticated calculator. However its true power abounds when applying such a computer algebra system to complex problems such as integrals, differential equations or algebraic system of equations that are hardly or even not solvable at all with pen and paper.

• E.g.: Differentiation

Just to get used to the syntax we regard a simple example. The differentiation symbol is the capital D:

? D

```
D[f, x] gives the partial derivative \partial f / \partial x.

D[f, {x, n}] gives the multiple derivative \partial^n f / \partial x^n.

D[f, x, y, ...] differentiates f successively with respect to x, y, ....

D[f, {{x<sub>1</sub>, x<sub>2</sub>, ...}] for a scalar f gives the vector derivative (\partial f / \partial x_1, \partial f / \partial x_2, ...).

D[f, {array}] gives a tensor derivative. \gg
```

When we compute the first derivative of a general function F[x], we get the output F'[x]. As described in the *Mathematica* documentation, the arguments (function and variable) of this operation are separated by a comma.

```
D[F[x], x]
F'[x]
```

We have to further specify the function to be derived in order to get a calculated output of course. As an example we define a function G in and compute ther first partial derivative with respecto to one variable,

```
G[x_, y_] := x * y
D[G[x, y], y]
```

the second partial derivative

```
D[G[x, y], {x, 2}]
```

or subsequent derivatives with respect to a list of variables.

```
D[G[x, y], x, y]
```

Simplify und Expand

?Simplify

Simplify[*expr*] performs a sequence of algebraic and other transformations on *expr*, and returns the simplest form it finds. Simplify[*expr*, *assum*] does simplification using assumptions. \gg

```
?FullSimplify
```

FullSimplify[expr] tries a wide range of transformations on

expr involving elementary and special functions, and returns the simplest form it finds. FullSimplify[expr, assum] does simplification using assumptions. \gg

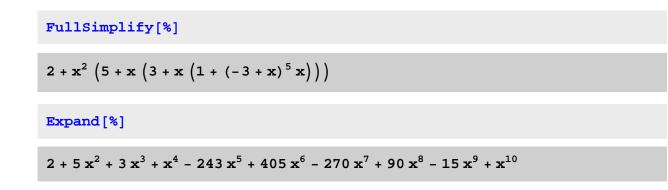
? Expand

Expand[*expr*] expands out products and positive integer powers in *expr*. Expand[*expr*, *patt*] leaves unexpanded any parts of *expr* that are free of the pattern *patt*. \gg

E.g.: Polynom

 $x * (x + 1)^{3} + (x^{2} - 3 * x)^{5} + x + 1 + x^{2} + (x - x^{2} + (x - 1)^{2})^{2}$

$$1 + x + x^{2} + x (1 + x)^{3} + ((-1 + x)^{2} + x - x^{2})^{2} + (-3x + x^{2})^{5}$$



Plots / Graphics / Figures - Basics

Plot

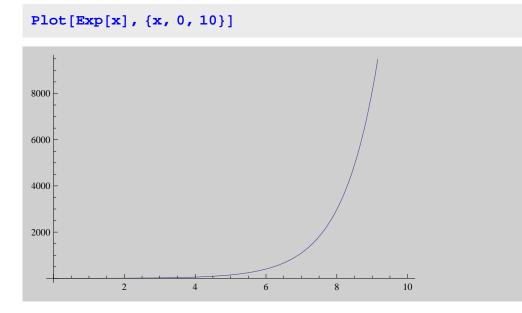
A major scientific tool in *Mathematica* is the manifold of plotting routines that help you to depict mathematical results grafically. The basic syntax for 2D graphs (as they are of course also done by muich simpler programs like gnuplot) is Plot[Argument, {Variables, Boundaries}]. These boundaries define the abscissa, the ordinate is scaled with the additional argument, namely PlotRange -> {Boundaries}.

?Plot*

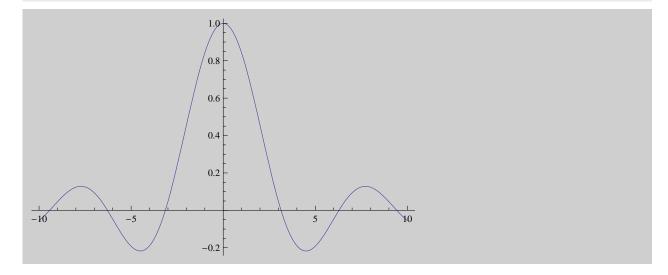
▼ System`

Plot	Plot3Matrix	PlotJoined	PlotLayout	PlotPoints	PlotRange- Clipping	PlotRegion
Plot3D	PlotDivisio- n	PlotLabel	PlotMarke- rs	PlotRange	PlotRange- Padding	PlotStyle

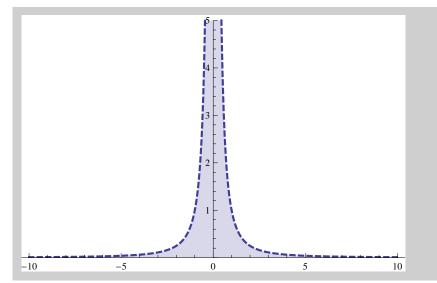
Plot Functions



Plot[Sin[x]/x, {x, -10, 10}]



```
Plot[1/x<sup>2</sup>, {x, -10, 10}, PlotRange \rightarrow {0, 5},
PlotStyle -> {Thick, Dashed}, Background \rightarrow White, Filling \rightarrow Automatic]
```



Dynamic Graphics

The two major commands for interactice plotting are:

? Dynamic

Dynamic[expr] represents an object that displays as the dynamically updated current value

of *expr*. If the displayed form of Dynamic[*expr*] is interactively changed or edited, an assignment

expr = *val* is done to give *expr* the new value *val* that corresponds to the displayed form.

Dynamic[expr, None] does not allow interactive changing or editing.

Dynamic[*expr*, *f*] continually evaluates *f*[*val*, *expr*] during interactive changing or editing of *val*.

Dynamic[*expr*, {f, f_{end} }] also evaluates $f_{end}[val, expr]$ when interactive changing or editing is complete.

Dynamic[*expr*, { f_{start} , $f_{, f_{end}}$] also evaluates $f_{start}[val, expr]$ when interactive changing or editing begins. \gg

? Manipulate

Manipulate[*expr*, {*u*, *u_{min}*, *u_{max}*}] generates a version

of *expr* with controls added to allow interactive manipulation of the value of *u*.

Manipulate[*expr*, {u, u_{min} , u_{max} , du}] allows the value of u to vary between u_{min} and u_{max} in steps du.

Manipulate[*expr*, {{ u, u_{init} }, $u_{min}, u_{max}, ...$ }] takes the initial value of u to be u_{init} .

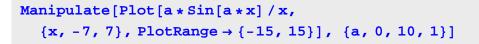
Manipulate[*expr*, {{ u, u_{init}, u_{lbl} }, ...}] labels the controls for u with u_{lbl} .

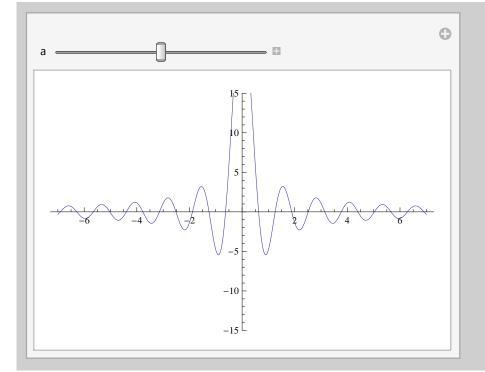
Manipulate[*expr*, $\{u_1, u_2, ...\}$] allows u to take on discrete values $u_1, u_2, ...$

Manipulate[*expr*, {*u*, …}, {*v*, …}, …] provides controls to manipulate each of the *u*, *v*, …

Manipulate[*expr*, $c_u \rightarrow \{u, ...\}, c_v \rightarrow \{v, ...\}, ...]$

links the controls to the specified controllers on an external device. \gg





Graphics und Show

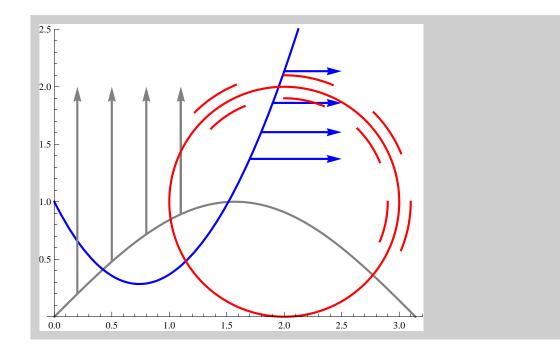
? Graphics

Graphics[primitives, options] represents a two-dimensional graphical image. >>

? Show

Show[graphics, options] shows graphics with the specified options added. Show[$g_1, g_2, ...$] shows several graphics combined. \gg

```
Show[Plot[Sin[x], \{x, 0, Pi\},
  AspectRatio \rightarrow Automatic, PlotStyle \rightarrow {Thick, Gray},
  Background \rightarrow White, PlotRange \rightarrow {0, 2.5}],
 Plot [Exp[-x] - x + x^2, {x, 0, Pi}, AspectRatio \rightarrow Automatic,
  PlotStyle \rightarrow {Thick, Blue},
  Background \rightarrow White, PlotRange \rightarrow {0, 2.5}],
 Graphics[{Thick, Gray, Arrow[{{0.2, Sin[0.2]}, {0.2, 2}}]}],
 Graphics[{Thick, Gray, Arrow[{{.5, Sin[.5]}, {.5, 2}}]}],
 Graphics[{Thick, Gray, Arrow[{{.8, Sin[.8]}, {.8, 2}}]}],
 Graphics [{Thick, Gray, Arrow [{{1.1, Sin[1.1]}, {1.1, 2}}]}],
 Graphics[{Thick, Gray, Arrow[{{1.1, Sin[1.1]}, {1.1, 2}}]}],
 Graphics[{Thick, Blue, Arrow[{{1.7, Exp[-1.7] - 1.7 + 1.7^2},
      \{2.5, Exp[-1.7] - 1.7 + 1.7^{2}\}\}\},
 Graphics[{Thick, Blue, Arrow[{{1.8, Exp[-1.8] - 1.8 + 1.8^2},
      \{2.5, Exp[-1.8] - 1.8 + 1.8^{2}\}\}\},
 Graphics[{Thick, Blue, Arrow[{{1.9, Exp[-1.9] - 1.9 + 1.9^2},
      \{2.5, Exp[-1.9] - 1.9 + 1.9^{2}\}\}],
 Graphics [{Thick, Blue, Arrow[{\{2, Exp[-2] - 2 + 2^2\},
      \{2.5, Exp[-2] - 2 + 2^2\}\}\},
 Graphics[{Thick, Red, Circle[{2, 1}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, 1.1, {-Pi/8, 0}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, 1.1, {Pi/8, 2*Pi/8}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, 1.1, {3*Pi/8, 4*Pi/8}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, 1.1, {5*Pi/8, 6*Pi/8}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, .9, {-Pi/8, 0}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, .9, {Pi/8, 2*Pi/8}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, .9, {3*Pi/8, 4*Pi/8}]}],
 Graphics[{Thick, Red, Circle[{2, 1}, .9, {5*Pi/8, 6*Pi/8}]}]
1
```



Linear Algebra - Calculus on Lists, Vectors, Matrices etc.

On The Difference Between Lists and Vectors

Handling Vectors, Matrices and Tensors

Whenever working with CAS respectively even more basic level of data processing such as using common programming languages, one has to keep in mind that a list of entries does not necessarily make a vector, nor does a two dimensional list make a tensor etc. From algebra we know that all tensorial quantities are only defined properly when also defining a base. This standard base is - as expected - the cartesian n-dimensional unit base if nothing else is specified.

A list of functions, numbers or otherwise entries is input via curly brackets and the comma as separator.

vec = {a, b, c, d}
{a, b, c, d}

? Dimensions

Dimensions[*expr*] gives a list of the dimensions of *expr*. Dimensions[*expr*, n] gives a list of the dimensions of *expr* down to level n. \gg

Dimensions[vec]

 $\{4\}$

Of course this concept can be used to arbitrarily interlace lists of lists etc.

Dimensions[tensor]

 $\{2, 4, 3\}$

• E.g.: The Identity Matrix

? IdentityMatrix

IdentityMatrix[n] gives the $n \times n$ identity matrix. \gg

```
M := IdentityMatrix[10]
```

Dimensions[M]

 $\{10, 10\}$

• E.g.: Automatic Filling of Lists

? Table

Table[*expr*, $\{i_{max}\}$] generates a list of i_{max} copies of *expr*.

Table[*expr*, {i, i_{max} }] generates a list of the values of *expr* when i runs from 1 to i_{max} .

Table[*expr*, {i, i_{min} , i_{max} }] starts with $i = i_{min}$.

Table[*expr*, {*i*, *i*_{min}, *i*_{max}, *di*}] uses steps *di*.

Table[*expr*, $\{i, \{i_1, i_2, ...\}\}$] uses the successive values $i_1, i_2, ...$

Table[*expr*, {*i*, *i*_{min}, *i*_{max}}, {*j*, *j*_{min}, *j*_{max}}, ...] gives a nested list. The list associated with *i* is outermost. \gg

H = Table[1 / (i + j - 1), {i, 1, 15}, {j, 1, 15}]; % // MatrixForm

1 12 13 14 15 16 17 18 19 1	1213141516171819101	1314151617181910111	1415161718191011111	15161718191011111111111111111111111111111111	$\frac{1}{6} \frac{1}{17} \frac{1}{18} \frac{1}{19} \frac{1}{11} \frac{1}{111} \frac{1}{111} \frac{1}{1111} \frac{1}{1111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{111111} \frac{1}{111111} \frac{1}{111111} \frac{1}{111111111} \frac{1}{1111111111$	$\frac{1}{7} \frac{1}{18} \frac{1}{19} \frac{1}{11} \frac{1}{111} \frac{1}{112} \frac{1}{111} \frac{1}{111} \frac{1}{1111} \frac{1}{1111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{11111} \frac{1}{111111} \frac{1}{111111} \frac{1}{1111111111$	$\begin{array}{c} 1\\8\\9\\9\\1\\10\\1\\11\\1\\2\\1\\1\\1\\1\\1\\1\\1\\1\\1\\1\\1\\1\\1$	$\frac{1}{9} \frac{1}{10} \frac{1}{11} \frac{1}{12} \frac{1}{13} \frac{1}{14} \frac{1}{15} \frac{1}{16} \frac{1}{17} \frac{1}{1}$	$\frac{1}{10}$ $\frac{1}{11}$ $\frac{1}{12}$ $\frac{1}{13}$ $\frac{1}{14}$ $\frac{1}{15}$ $\frac{1}{16}$ $\frac{1}{17}$ $\frac{1}{18}$ $\frac{1}{18}$ $\frac{1}{11}$	$\begin{array}{c} 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ $	$ \begin{array}{c} 1\\ 12\\ -\\ 13\\ -\\ 14\\ -\\ 15\\ -\\ 16\\ -\\ 17\\ -\\ 18\\ -\\ 19\\ -\\ 20\\ -\\ 1 \end{array} $	$\frac{1}{13} \frac{1}{14} \frac{1}{15} \frac{1}{16} \frac{1}{17} \frac{1}{18} \frac{1}{19} \frac{1}{20} \frac{1}{21} \frac{1}{11}$	$\frac{1}{14} \frac{1}{15} \frac{1}{16} \frac{1}{17} \frac{1}{18} \frac{1}{19} \frac{1}{20} \frac{1}{21} \frac{1}{22} \frac{1}{21}$	$\frac{1}{15} \frac{1}{16} \frac{1}{17} \frac{1}{18} \frac{1}{19} \frac{1}{20} \frac{1}{21} \frac{1}{22} \frac{1}{23} \frac{1}{23}$	
5				9 1		11		13			16 1		18 1		
6				10											
$\frac{1}{7}$	<u>1</u> 8	<u>1</u> 9	$\frac{1}{10}$	$\frac{1}{11}$	$\frac{1}{12}$	$\frac{1}{13}$	$\frac{1}{14}$	$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	$\frac{1}{19}$	$\frac{1}{20}$	$\frac{1}{21}$	
<u>1</u> 8												1			
<u>1</u> 9											$\frac{1}{20}$		$\frac{1}{22}$		
$\frac{1}{10}$	$\frac{1}{11}$	$\frac{1}{12}$	$\frac{1}{13}$	$\frac{1}{14}$	$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	$\frac{1}{19}$	$\frac{1}{20}$	$\frac{1}{21}$	$\frac{1}{22}$	$\frac{1}{23}$	<u>1</u> 24	
$\frac{1}{11}$	$\frac{1}{12}$	$\frac{1}{13}$	$\frac{1}{14}$	$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	$\frac{1}{19}$	$\frac{1}{20}$	$\frac{1}{21}$	$\frac{1}{22}$	$\frac{1}{23}$	$\frac{1}{24}$	<u>1</u> 25	
$\frac{1}{12}$	$\frac{1}{13}$	$\frac{1}{14}$	$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	<u>1</u> 19	$\frac{1}{20}$	$\frac{1}{21}$	$\frac{1}{22}$	<u>1</u> 23	$\frac{1}{24}$	<u>1</u> 25	$\frac{1}{26}$	
$\frac{1}{13}$	$\frac{1}{14}$	$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	<u>1</u> 19	$\frac{1}{20}$	$\frac{1}{21}$	$\frac{1}{22}$	$\frac{1}{23}$	$\frac{1}{24}$	$\frac{1}{25}$	$\frac{1}{26}$	<u>1</u> 27	
$\frac{1}{14}$	$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	$\frac{1}{19}$	$\frac{1}{20}$	$\frac{1}{21}$	$\frac{1}{22}$	$\frac{1}{23}$	$\frac{1}{24}$	$\frac{1}{25}$	$\frac{1}{26}$	$\frac{1}{27}$	<u>1</u> 28	
$\frac{1}{15}$	$\frac{1}{16}$	$\frac{1}{17}$	$\frac{1}{18}$	$\frac{1}{19}$	$\frac{1}{20}$	$\frac{1}{21}$	$\frac{1}{22}$	$\frac{1}{23}$	$\frac{1}{24}$	1 25	$\frac{1}{26}$	$\frac{1}{27}$	1 28	1 29	
10															

? Subscript

Subscript[x, y] is an object that formats as x_y . Subscript[x, y₁, y₂, ...] formats as $x_{y_1,y_2,...} \gg$ Table[Subscript[m, i, j], {i, 3}, {j, 3}] // MatrixForm $\begin{pmatrix} m_{1,1} & m_{1,2} & m_{1,3} \\ m_{2,1} & m_{2,2} & m_{2,3} \\ m_{3,1} & m_{3,2} & m_{3,3} \end{pmatrix}$

Coordinate Systems + Vector Calculus

Since the topic of coordinate systems is especially interesting in physical and astrophysical applications, we want to take a look at the implemented functionalities in *Mathematica*. A number of packages in *Mathematica* are not loaded into the Kernel by default (which makes the startup faster) but have to be loaded on demand. The *VectorAnalysis* package is one of those - other exaples can be found here: tutorial/PackagesForSymbolicMathematics.

The VectorAnalysis Package

Loading the package

```
Needs["VectorAnalysis`"]
```

enables a number of additional commands. E.g. with

```
CoordinateSystem
```

Cartesian

one can inquire the momentarily used coordinate system. As mentioned before, this is cartesian by default. When we change to a spherical coordinate system (remark: "American" coordinate ranges by default)

```
SetCoordinates[Spherical[r, \theta, \phi]]
```

```
Spherical[r, \theta, \phi]
```

and compute the divergence of the unit vector in r-direction, (1,0,0), we get the well known result.

Div[{1, 0, 0}]

2 r

```
JacobianMatrix[Spherical] // MatrixForm
```

```
 \begin{pmatrix} \cos[\phi] \sin[\theta] & r \cos[\theta] \cos[\phi] & -r \sin[\theta] \sin[\phi] \\ \sin[\theta] \sin[\phi] & r \cos[\theta] \sin[\phi] & r \cos[\phi] \sin[\theta] \\ \cos[\theta] & -r \sin[\theta] & 0 \end{pmatrix}
```

Just as further example for some functionalities of that package, we calculate the unit volume of a cylindre with radius and height one by the differential geometric rule as the integral over the Jacobian determinant.

```
SetCoordinates[Cylindrical[r, θ, z]]
Cylindrical[r, θ, z]
Integrate[JacobianDeterminant[Cylindrical],
    {r, 0, 1}, {θ, 0, 2 * π}, {z, 0, 1}]
```

π

Just to check, we compute the divergence of the unit vector in x-direction for cartesian coordinates

```
SetCoordinates[Cartesian]
Cartesian[Xx, Yy, Zz]
Div[{1, 0, 0}]
0
```

which vanishes of course.

Scalar Product, Cross Product

Even without the *VectorAnalysis* package activated, there are vector commands loaded by default, such as the scalar (inner) product of two vectors, input via the dot (.).

```
vec = {a, b, c}
{a, b, c}
```

 $\mathbf{vec.vec}$ $\mathbf{a}^2 + \mathbf{b}^2 + \mathbf{c}^2$

With the star * the entries of the list are multiplied pairwise.

```
\frac{\mathbf{vec} \ast \mathbf{vec}}{\left\{a^2, b^2, c^2\right\}}
```

The cross profuct (vector product) is set with the command Cross.

```
Cross[vec, vec]
{0, 0, 0}
```

Since a vector is parallel to itself, the cross product has to vanish.

```
Cross[{1,0,0}, {0,1,0}]
```

 $\{0, 0, 1\}$

The cross product between two unit base vectors in three dimensions yields the third unit base vector.

Solving Sets of Equations

optional: Solving Linear Sets of Equations

One of the most importand application of computer algebra and numerical codes is solving systems of equations. Wether you want to solve a complicated switching circuit by solving the Kirchhoff rules or you look for the numerical solution of differential equations, mathematically these problems reduce to solving (huge) sets of linear equations or - even more basic - it means to invert big matrices. Although CAS and numerical schemes are very powerful tools for computationally expensive problems, there are of course limitations as well. This shall be demonstrated with the help of a little example.

The main command for solving linear systems of equations is

?LinearSolve

```
LinearSolve[m, b] finds an x which solves the matrix equation m.x == b.
LinearSolve[m] generates a LinearSolveFunction[...] which can be applied repeatedly to different b. \gg
```

which solves equations of the form m.x=b.

• E.g.: Hilbert - Matrix

We ragard an arbitrary real vector b (filled with random real numbers between 0 and 100)

```
b = Table[Random[Integer, 100], {n, 1, 15}]
{31, 84, 7, 64, 98, 93, 11, 84, 30, 94, 51, 62, 75, 11, 9}
```

and solve the system H.x=b, i.e. we want to determine the solution vector x. The matrix H was defined above in subsection "Automatic Filling of Lists ".

```
LinearSolve[H, b] // MatrixForm
```

```
- 3 734 071 933 185
751 754 904 677 280
- 37 714 435 829 386 680
828 864 504 280 612 800
- 9 984 977 804 685 904 020
74 111 982 969 427 603 200
- 362 869 877 239 232 683 320
1 221 043 396 114 981 604 880
- 2 889 102 402 497 160 559 710
4 847 877 238 595 981 990 400
- 5 737 637 243 526 263 875 800
4 682 450 439 923 249 994 000
- 2 507 202 365 724 910 608 300
792 653 569 836 038 568 000
- 112 131 660 922 158 101 400
```

On some computers this may take quite some time since the determinant of this matrix, also known as Hilbert-Matrix, gets numerically very small with increasing problem size. From the theory of linear algebra we know that a system of linear equations is only solvable when the determinant is non-zero. Computationally, matrix inversion gets more and more expensive, the smaller the determinant. ?Det

Det[m] gives the determinant of the square matrix m. \gg

```
Det[H] // N
```

```
1.05854 \times 10^{-124}
```

The determinant of the 15-dim. Hilbert-Matrix is "practically" zero. The higher dimensional H, the smaller gets its determinant and the more difficult gets its inversion.

?HilbertMatrix

HilbertMatrix[*n*] gives the *n*×*n* Hilbert matrix with elements of the form 1/(i + j - 1). HilbertMatrix[{*m*, *n*}] gives the *m*×*n* Hilbert matrix. \gg

```
Det[HilbertMatrix[50]] // N
```

 $1.392615568935140 \times 10^{-1466}$

Clear["Global`*"]

Solving Coupled Systems of Equations

Clearly we are often also confronted with nonlinear sets of coupled equations, where we cannot express the problem as sketched before. In this case, we apply the command

? Solve

Solve[*expr*, *vars*] attempts to solve the system *expr* of equations or inequalities for the variables *vars*. Solve[*expr*, *vars*, *dom*] solves over the domain *dom*. Common choices of *dom* are Reals, Integers, and Complexes. >>

in which documentation entry it states already indicatively that it "attempts to solve" the problem posed. *Mathematica* has implemented a variety of algorithms that are tried out.

• E.g. : System of three linear equations

Solve[{3 * a == b, 2 * a == c, c == 1}, {a, b, c}] { $\left\{ \left\{ a \rightarrow \frac{1}{2}, b \rightarrow \frac{3}{2}, c \rightarrow 1 \right\} \right\}$

• E.g.: System of three nonlinear equations

$$\begin{split} & \left\{ \mathbf{a} \to -\frac{1}{\sqrt{2}} , \mathbf{b} \to -\frac{\mathbf{\dot{a}}\sqrt{3}}{2^{3/4}} , \mathbf{c} \to \mathbf{1} \right\}, \left\{ \mathbf{a} \to -\frac{1}{\sqrt{2}} , \mathbf{b} \to \frac{\mathbf{\dot{a}}\sqrt{3}}{2^{3/4}} , \mathbf{c} \to \mathbf{1} \right\}, \\ & \left\{ \mathbf{a} \to \frac{1}{\sqrt{2}} , \mathbf{b} \to -\frac{\sqrt{3}}{2^{3/4}} , \mathbf{c} \to \mathbf{1} \right\}, \left\{ \mathbf{a} \to \frac{1}{\sqrt{2}} , \mathbf{b} \to \frac{\sqrt{3}}{2^{3/4}} , \mathbf{c} \to \mathbf{1} \right\}, \\ & \left\{ \mathbf{a} \to -\sqrt{-\frac{1}{4} - \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \mathbf{\dot{a}} \sqrt{\frac{3}{2}} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to -\sqrt{-\frac{1}{4} - \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to \frac{1}{2} \mathbf{\dot{a}} \sqrt{\frac{3}{2}} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} - \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \sqrt{\frac{3}{2}} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} - \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \sqrt{\frac{3}{2}} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} + \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \mathbf{\dot{a}} \sqrt{\frac{3}{2}} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to -\sqrt{-\frac{1}{4} + \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \mathbf{\dot{a}} \sqrt{\frac{3}{2}} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} + \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \mathbf{\dot{a}} \sqrt{\frac{3}{2}} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} + \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \sqrt{\frac{3}{2}} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} + \frac{\mathbf{\dot{a}}\sqrt{3}}{4}} , \mathbf{b} \to -\frac{1}{2} \sqrt{\frac{3}{2}} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \\ & \left\{ \mathbf{a} \to \sqrt{-\frac{1}{4} + \frac{\mathbf{\dot{a}}\sqrt{3}}{4} , \mathbf{b} \to -\frac{1}{2} \sqrt{\frac{3}{2}} \left(-\mathbf{1} + \mathbf{\dot{a}}\sqrt{3} \right)^{3/4} , \mathbf{c} \to \frac{1}{2} \left(-\mathbf{1} - \mathbf{\dot{a}}\sqrt{3} \right) \right\}, \end{aligned}$$

Mathematica will list all found solutions also if they sometimes not usable for our purposes because they are unphysical or violate some other conditions. In this case we frequently have to come back to

pen and paper in order to pick the "right" results.

Some more useful commands concerning linear algebra:

?RandomReal

RandomReal[] gives a pseudorandom real number in the range 0 to 1. RandomReal[$\{x_{min}, x_{max}\}$] gives a pseudorandom real number in the range x_{min} to x_{max} . RandomReal[x_{max}] gives a pseudorandom real number in the range 0 to x_{max} . RandomReal[range, n] gives a list of n pseudorandom reals. RandomReal[$range, \{n_1, n_2, ...\}$] gives an $n_1 \times n_2 \times ...$ array of pseudorandom reals. \gg

 $A = RandomReal[\{-1, 1\}, \{5, 5\}]$

```
{{-0.474727, 0.388645, -0.461371, 0.938493, 0.950533},
{0.830478, 0.139342, -0.801181, 0.0834233, 0.259048},
{0.606089, 0.750426, -0.0652498, 0.50112, -0.928461},
{-0.903335, 0.207855, 0.368359, -0.051829, 0.0604615},
{0.0480989, -0.359201, 0.128467, 0.236191, -0.0770996}}
```

? MatrixRank

MatrixRank[m] gives the rank of the matrix m. \gg

```
MatrixRank[A]
```

5

? Eigenvalues

Eigenvalues[*m*] gives a list of the eigenvalues of the square matrix *m*. Eigenvalues[{*m*, *a*}] gives the generalized eigenvalues of *m* with respect to *a*. Eigenvalues[*m*, *k*] gives the first *k* eigenvalues of *m*. Eigenvalues[{*m*, *a*}, *k*] gives the first *k* generalized eigenvalues. \gg

Eigenvalues[A]

{0.195529 + 1.07151 ±, 0.195529 - 1.07151 ±, -0.325532 + 0.509743 ±, -0.325532 - 0.509743 ±, -0.269558}

? Eigenvectors

Eigenvectors[*m*] gives a list of the eigenvectors of the square matrix *m*. Eigenvectors[$\{m, a\}$] gives the generalized eigenvectors of *m* with respect to *a*. Eigenvectors[*m*, *k*] gives the first *k* eigenvectors of *m*. Eigenvectors[$\{m, a\}, k$] gives the first *k* generalized eigenvectors. \gg

Eigenvectors[A]

 $\{ \{ 0.144597 + 0.32199 \, \dot{n}, \, 0.647119 + 0. \, \dot{n}, \, 0.0223833 - 0.456948 \, \dot{n}, \\ -0.391941 - 0.0945935 \, \dot{n}, -0.127755 + 0.261649 \, \dot{n} \}, \\ \{ 0.144597 - 0.32199 \, \dot{n}, \, 0.647119 + 0. \, \dot{n}, \, 0.0223833 + 0.456948 \, \dot{n}, \\ -0.391941 + 0.0945935 \, \dot{n}, -0.127755 - 0.261649 \, \dot{n} \}, \\ \{ -0.0352433 - 0.480426 \, \dot{n}, -0.327103 - 0.0011468 \, \dot{n}, \\ -0.259849 - 0.380617 \, \dot{n}, \, 0.542821 + 0. \, \dot{n}, -0.276221 - 0.278583 \, \dot{n} \}, \\ \{ -0.0352433 + 0.480426 \, \dot{n}, -0.327103 + 0.0011468 \, \dot{n}, \\ -0.259849 + 0.380617 \, \dot{n}, \, 0.542821 + 0. \, \dot{n}, -0.276221 + 0.278583 \, \dot{n} \}, \\ \{ 0.320862, \, 0.369529, \, 0.656308, -0.272299, \, 0.505578 \} \}$

? CharacteristicPolynomial

CharacteristicPolynomial[m, x] gives the characteristic polynomial for the matrix m.

CharacteristicPolynomial[$\{m, a\}, x$] gives the generalized characteristic polynomial with respect to a. \gg

CP[x_] = CharacteristicPolynomial[A, x]

 $-0.116983 - 0.603626 x - 0.979111 x^{2} - 1.36765 x^{3} - 0.529564 x^{4} - x^{5}$

The eigenvalues of a matrix (resp. a linear map) are the zeros of the characteristical polynomial which we can probe:

```
CP[Eigenvalues[A]]
```

 $\{2.22045 \times 10^{-16} + 0. \text{ i}, 2.22045 \times 10^{-16} + 0. \text{ i}, \\ -2.77556 \times 10^{-17} + 5.55112 \times 10^{-17} \text{ i}, \\ -2.77556 \times 10^{-17} - 5.55112 \times 10^{-17} \text{ i}, -1.73472 \times 10^{-17} \}$

... is approximately zweo.

Analysis - Working with Functions, Derivatives, Integrals

Introductory Remarks

Mathematical Entities in Mathematica

As mentioned before, *Mathematica* has some syntactic idiosyncrasies. As an example we regard one of the most beautiful formulas in mathematics:

DONT :

```
e^ (i * pi) = -1

e<sup>i pi</sup> = -1

DO:

E^ (I * Pi) = -1

True

? E

E is the exponential constant e (base of natural logarithms), with numerical value \approx 2.71828. \gg

? I

I represents the imaginary unit \sqrt{-1}. \gg

? Pi

Pi is \pi, with numerical value \approx 3.14159. \gg
```

? Infinity

Infinity or ∞ is a symbol that represents a positive infinite quantity. \gg

• optional: Natural Constants etc.

<< PhysicalConstants`
SpeedOfLight
299 792 458 Meter Second
FineStructureConstant
0.00729735
AgeOfUniverse
4.7×10^{17} Second
MagneticFluxQuantum
2.06783×10 ⁻¹⁵ Weber

Important Embedded Functions

Clearly the most important functions are implemented in *Mathematica;* as mentioned before all these commands begin with a capital letter. Some Examples:

?Sin

Sin[z] gives the sine of z. \gg

? Log

Log[z] gives the natural logarithm of z (logarithm to base e). Log[b, z] gives the logarithm to base b. \gg

? Gamma

Gamma[z] is the Euler gamma function $\Gamma(z)$.

Gamma[a, z] is the incomplete gamma function $\Gamma(a, z)$.

Gamma[a, z_0 , z_1] is the generalized incomplete

gamma function $\Gamma(a, z_0) - \Gamma(a, z_1)$. It is also a unit of magnetic flux density. \gg

?DiracDelta

DiracDelta[x] represents the Dirac delta function $\delta(x)$. DiracDelta[x₁, x₂, ...] represents the multidimensional Dirac delta function $\delta(x_1, x_2, ...)$. \gg

Series

In order to get used to handling series, we examine a frequent application, namely determining the limit of a series.

```
Clear["Global`*"]
(* please enter this input to delete all previous definitions
which would partially conflict with the upcoming section *)
```

We can define series analogously to functions

or recursively

b[n_] := b[n - 1] * b[n - 2] b[0] := 1 b[1] := 2 b[2] := 2 and determine the limit or generate a list of entries.

```
?Limit
```

Limit[*expr*, $x \rightarrow x_0$] finds the limiting value of *expr* when x approaches x_0 .

```
Limit[a[n], n → Infinity]

@
Table[b[n], {n, 0, 10}]

{1, 2, 2, 4, 8, 32, 256, 8192,
    2097152, 17179869184, 36028797018963968}
```

Of course also sums are implemented im Mathematica

? Sum

Sum[f, {i, i_{max}}] evaluates the sum $\sum_{i=1}^{i_{max}} f$. Sum[f, {i, i_{min}, i_{max}}] starts with $i = i_{min}$. Sum[f, {i, i_{min}, i_{max}, di}] uses steps di. Sum[f, {i, i₁, i₂, ...}] uses successive values $i_1, i_2, ...$. Sum[f, {i, i_{min}, i_{max}}, {j, j_{min}, j_{max}}, ...] evaluates the multiple sum $\sum_{i=i_{min}}^{i_{max}} \sum_{j=j_{min}}^{j_{max}} ... f$. Sum[f, i] gives the indefinite sum $\sum_{i} f$. \gg Sum[x^n/(n!^2), {n, 0, Infinity}] Bessell[0, 2 \sqrt{x}] ?Bessell

BesselI[n, z] gives the modified Bessel function of the first kind $I_n(z)$. \gg

 $\frac{\operatorname{e^{x} \operatorname{Gamma}[1+n, x]}}{n!}$

and especially useful is also the Series command which expands a function into its Taylor series.

```
? Series

Series[f, {x, x_0, n}] generates a power series expansion for f about the point x = x_0 to order (x - x_0)^n.

Series[f, {x, x_0, n_x}, {y, y_0, n_y}, ...] successively finds series expansions with respect to x, then y, etc. \gg

Series[Sin[x], {x, 0, 15}]

x - \frac{x^3}{6} + \frac{x^5}{120} - \frac{x^7}{5040} + \frac{x^9}{362\,880} - \frac{x^{11}}{39\,916\,800} + \frac{x^{13}}{6\,227\,020\,800} - \frac{x^{15}}{1\,307\,674\,368\,000} + O[x]^{16}
```

Differentiation and Integration

Integration

Basic differentiation syntax was presented already in section I/O III. Integration commands are analogous

```
Clear["Global`*"]
(* please enter this input to delete all previous definitions
  which would partially conflict with the upcoming section *)
```

? Integrate

Integrate[f, x] gives the indefinite integral $\int f dx$. Integrate[f, {x, x_{min} , x_{max} }] gives the definite integral $\int_{x_{min}}^{x_{max}} f dx$. Integrate[f, {x, x_{min} , x_{max} }, {y, y_{min} , y_{max} }, ...] gives the multiple integral $\int_{x_{min}}^{x_{max}} dx \int_{y_{min}}^{y_{max}} dy ... f$. \gg

E.g.: Some Integrals

```
Integrate[Sin[x], x]
-Cos[x]
Integrate[E^(x^2), x]
\frac{1}{2}\sqrt{\pi} \operatorname{Erfi}[x]
? Erfi
```

 $\operatorname{Erfi}[z]$ gives the imaginary error function $\operatorname{erf}(iz)/i$. \gg

```
Integrate[Sin[x] * Cos[x], {x, -Pi, Pi}]
0
Integrate[E^(-x), {x, 0, Infinity}]
1
```

Differential Equations

Solving Ordinary Differential Equations (ODEs)

Solving differential equations is another major strenght of CAS. While solving an ODE can require a sophisticated ansatz and several analytic techniques, *Mathematica* is a lot faster in giving results with help of the command DSolve.

```
Clear["Global`*"]
(* please enter this input to delete all previous definitions
which would partially conflict with the upcoming section *)
```

• E.g.: Solving ODEs without boundary condition

? DSolve

DSolve[eqn_1, y, x] solves a differential equation for the function y_i with independent variable x. DSolve[$eqn_1, eqn_2, ...$], $\{y_1, y_2, ...$], x] solves a list of differential equations. DSolve[$eqn_i, y_i, \{x_1, x_2, ...\}$] solves a partial differential equation. \gg

```
DSolve[y'[x] + y[x] = 0, y[x], x]
```

```
\{\{y[x] \rightarrow e^{-x} C[1]\}\}
```

E.g.: Solving ODEs with boundary condition

 $DSolve[{z'[x] + z[x] == 0, z[0] == 1}, z[x], x]$

 $\{\{\mathbf{z} \,[\,\mathbf{x}\,] \rightarrow \mathbb{e}^{-\mathbf{x}}\}\}$

• E.g.: Solving systems of ODEs

eqn1 := s'[x] + t[x] == 0 eqn2 := t'[x] + s[x] == 0

 $DSolve[{eqn1, eqn2}, {s[x], t[x]}, x]$

$$\left\{ \left\{ s\left[x\right] \rightarrow \frac{1}{2} e^{-x} \left(1 + e^{2x}\right) C\left[1\right] - \frac{1}{2} e^{-x} \left(-1 + e^{2x}\right) C\left[2\right], \\ t\left[x\right] \rightarrow -\frac{1}{2} e^{-x} \left(-1 + e^{2x}\right) C\left[1\right] + \frac{1}{2} e^{-x} \left(1 + e^{2x}\right) C\left[2\right] \right\} \right\}$$

• E.g.: Numerical solutions of ODEs

Whenever *Mathematica* fails to find a closed analytic solution of an ODE, such as the following example shows

$$DSolve[y''[x] + y'[x] + y[x] * (1 + y[x]) = 0, y[x], x]$$
$$DSolve[y[x] (1 + y[x]) + y'[x] + y''[x] = 0, y[x], x]$$

there is the possibility to look for solutions numerically. Iterative algorithms implemented in Mathe-

matica are capable of finding numerical solutions of ODEs.

? NDSolve

NDSolve[*eqns*, y_i { x_i x_{min} , x_{max} }] finds a numerical solution to the ordinary differential

equations *eqns* for the function *y* with the independent variable *x* in the range x_{min} to x_{max} . NDSolve[*eqns*, *y*, {*x*, *x_{min}*, *x_{max}*}, {*t*, *t_{min}*, *t_{max}*}] finds a numerical solution to the partial differential equations *eqns*.

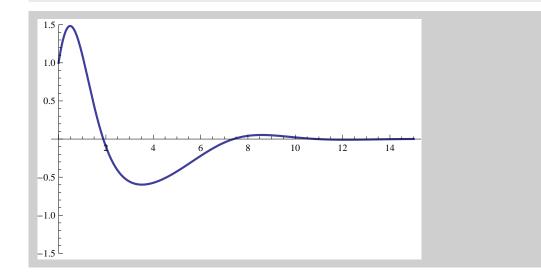
NDSolve[*eqns*, { y_1 , y_2 , ...}, { x_i , x_{min} , x_{max} }] finds numerical solutions for the functions y_i .

sol = NDSolve[{y[x] (1 + y[x]) + y'[x] + y''[x] == 0, y[0] == 1, y'[0] == 2},
y[x], {x, 0, 15}]

```
\{\{y[x] \rightarrow InterpolatingFunction[\{\{0., 15.\}\}, <>][x]\}\}
```

The result is output as "InterpolatingFunction" meaning that the function is only known at those points where the algorithm has provided a numerical result.

```
Plot[Evaluate[y[x] /. sol], {x, 0, 15},
PlotRange \rightarrow 1.5, PlotStyle \rightarrow {Thick}, Background \rightarrow White]
```



CAS: Alternatives

Mathematica is a comprehensive computer algebra system, however it is a proprietary product. There are several free open source alternatives:

Axiom:http://axiom-wiki.newsynthesis.org/FrontPageScilab:http://www.scilab.org/

Octave:http://www.gnu.org/software/octave/Maxima:http://maxima.sourceforge.net/Wiris:http://www.wiris.com/Geogebra:http://www.geogebra.org/cms/